

# Pole swapping methods for the eigenvalue problem

Rational QR algorithms

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# Overview

## Introduction

- Generalized eigenvalue problems

- Bulge chasing

## Pole swapping

- Rational Krylov

- Rational QZ

- Rational accelerated subspace iteration

## Multishift, multipole rational QZ

## Conclusion

## Introduction

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# Generalized eigenvalue problems

- Let  $A, B \in \mathbb{F}^{n \times n}$  define a *matrix pair*  $(A, B)$  or *matrix pencil*  $A - \lambda B$ .
- Regular:  $\det(A - \lambda B) \neq 0$ .
- Generalized eigenvalue problem:

$$A\mathbf{x} = \lambda B\mathbf{x}, \quad \lambda \in \bar{\mathbb{C}} := \mathbb{C} \cup \{\infty\}.$$

# Generalized eigenvalue problems

- For a regular matrix pencil  $A - \lambda B$  there exists unitary matrices  $Q$  and  $Z$  such that

$$S - \lambda T = Q^*(A - \lambda B)Z$$

with  $S - \lambda T$  upper triangular and  $\Lambda(A, B) = \{s_{11}/t_{11}, s_{22}/t_{22}, \dots\}$ .

- The **QZ method** (Moler-Stewart, 1973) is the default algorithm to compute the generalized Schur decomposition.

- The QZ method generalizes the QR method of (Francis, 1961-62) for the standard eigenvalue problem
- It is a **bulge chasing** algorithm which consists out of two phases:
  1. **Initial (direct) reduction** to equivalent Hessenberg, upper triangular form

$$H - \lambda R = Q^*(A - \lambda B)Z$$

2. **Iterative bulge chasing** phase to compute (real) generalized Schur decomposition

$$S - \lambda T = Q^*(A - \lambda B)Z$$

## Bulge chasing =

- Motivated by **implicit Q theorems**  
⇒ iterates are uniquely determined by  $\mathbf{q}_1 = \rho(AB^{-1})\mathbf{e}_1$
- Nested subspace iteration with a change of basis accelerated by **polynomials** (shifts) (Elsner-Watkins, 1991; Watkins, 1993)

→ These results are based on a connection with **Krylov subspaces**.



## Pole swapping

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Polynomial	Rational
<p><u>Krylov subspace</u></p> $\mathcal{K}_{m+1}(A, \mathbf{v}) := \mathcal{R}(\mathbf{v}, A\mathbf{v}, \dots, A^m\mathbf{v})$	<p><u>rational Krylov subspace</u></p> $\mathcal{K}_{m+1}^{\text{rat}}(A, \mathbf{v}, \Xi) := q(A)^{-1}\mathcal{K}_{m+1}(A, \mathbf{v})$ <ul style="list-style-type: none"> <li>• <math>\Xi = (\xi_1, \dots, \xi_m) \subset \bar{\mathbb{C}} \setminus \Lambda</math></li> <li>• <math>q(z) = \prod_{\xi_i \neq \infty} (z - \xi_i)</math></li> </ul>
<p><u>Arnoldi Decomposition</u> (Arnoldi, 1951)</p> $AV_m = V_{m+1}\underline{H}_m$	<p><u>rational Arnoldi</u> (Ruhe, 1998)</p> $AV_{m+1}\underline{K}_m = V_{m+1}\underline{L}_m$ <ul style="list-style-type: none"> <li>• <math>\ell_{i+1,i}/k_{i+1,i} = \xi_i</math></li> </ul>
<p><u>Uniqueness</u></p> $\mathbf{v} \text{ fixed} \Leftrightarrow (V_{m+1}, \underline{H}_m) \text{ unique}$	<p><u>Uniqueness</u> (Berljafa-Güttel, 2015)</p> $\mathbf{v} \text{ and } \Xi \text{ fixed} \Leftrightarrow (V_{m+1}, \underline{K}_m, \underline{L}_m) \text{ unique}$

## Berljafa-Güttel (2015)

Two methods to change the poles in a rational Arnoldi decomposition

$$AV_{m+1}K_m = V_{m+1}L_m$$

- Implicitly by changing  $\mathbf{v}_1$
- Explicitly by pole swapping

⇒ Equivalent if  $\mathcal{R}(V_{m+1})$  is fixed.

## C.-Meerbergen-Vandebril (2019a)

The pole swapping technique can be used as a direct method for the eigenvalue problem: rational QZ algorithm.

## Hessenberg pencils

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## Hessenberg pencils

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$B$

## Hessenberg pencils



$$\begin{matrix}
 A & & B \\
 \text{pole tuple } \Xi = & \left( \frac{\textcircled{1}}{\textcircled{a}}, \frac{\textcircled{2}}{\textcircled{b}}, \dots \right) \subset \bar{\mathbb{C}}
 \end{matrix}$$

# Rational QZ: an example

## Introducing a shift



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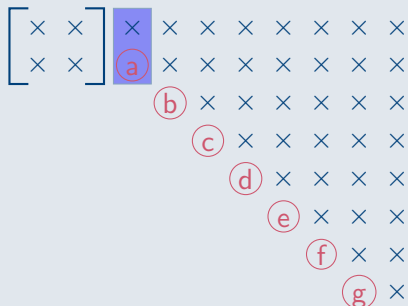
*B*

# Rational QZ: an example

## Introducing a shift



$A$



$B$

$$\begin{bmatrix} \times \\ \textcircled{1} \end{bmatrix} \neq \gamma \begin{bmatrix} \times \\ \textcircled{a} \end{bmatrix} !$$



# Rational QZ: an example

## Introducing a shift



*A*

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*B*

# Rational QZ: an example

## Swapping poles



*A*

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*B*

## Swapping poles

Classical problem in NLA:

### Reordering generalized Schur form

(Van Dooren, 1981), (Kågström, 1993), (C.-Mach-Vandebril-Watkins, 2019)

$$\begin{array}{|c|} \hline \frac{\oplus}{\ominus} \neq \frac{\textcircled{2}}{\textcircled{b}} ! \\ \hline \end{array} \quad \begin{array}{|c|} \hline \frac{\oplus}{\ominus} \neq \frac{0}{0} ! \\ \hline \end{array} \quad \begin{array}{|c|} \hline \frac{\textcircled{2}}{\textcircled{b}} \neq \frac{0}{0} ! \\ \hline \end{array}$$

$$\Rightarrow Q^* = \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix}, Z = \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix}$$

# Rational QZ: an example

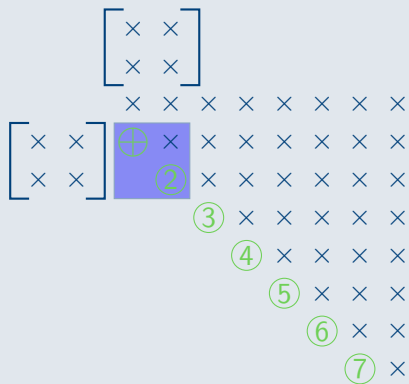
## Swapping poles

Table 1: Distribution of errors  $\hat{a}_{21}/\|A\|$  and  $\hat{b}_{21}/\|B\|$  for our method, Van Dooren's method, and the Sylvester method.

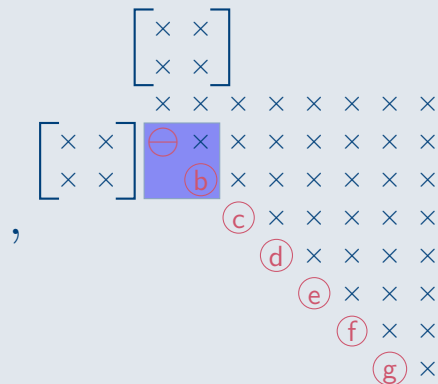
$\hat{x}_{21}/\ X\ $		$[0, 10^{-16}]$	$(10^{-16}, 10^{-15}]$	$(10^{-15}, 10^{-10}]$	$(10^{-10}, 10^{-5}]$	$(10^{-5}, 10^0]$
Our method	<i>A</i>	99.71%	0.29%	0%	0%	0%
	<i>B</i>	99.85%	0.15%	0%	0%	0%
Van Dooren	<i>A</i>	98.19%	0.55%	0.93%	0.27%	0.06%
	<i>B</i>	98.19%	0.55%	0.93%	0.27%	0.06%
Sylvester	<i>A</i>	93.34%	5.88%	0.57%	0.17%	0.04%
	<i>B</i>	93.34%	5.88%	0.57%	0.17%	0.04%

# Rational QZ: an example

## Swapping poles



*A*



*B*

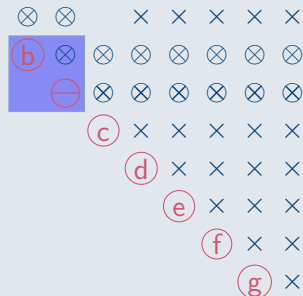
# Rational QZ: an example

## Swapping poles



*A*

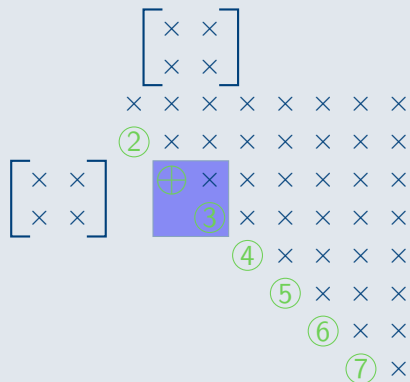
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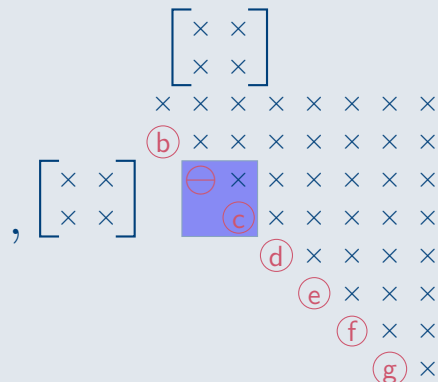
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# Rational QZ: an example

## Swapping poles



*A*



*B*

# Rational QZ: an example

## Swapping poles



*A*

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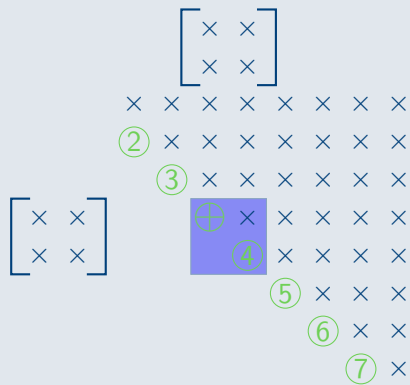


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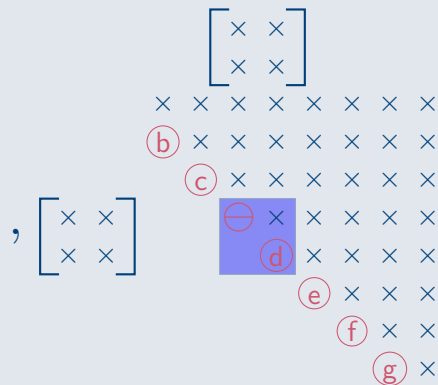


# Rational QZ: an example

## Swapping poles



*A*



*B*

# Rational QZ: an example

## Swapping poles



*A*

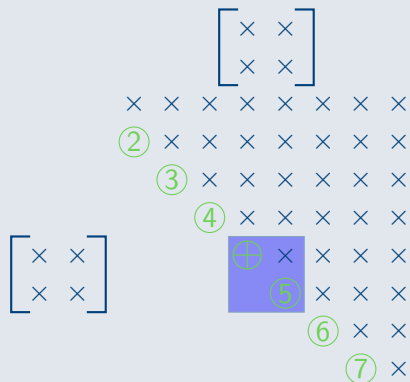
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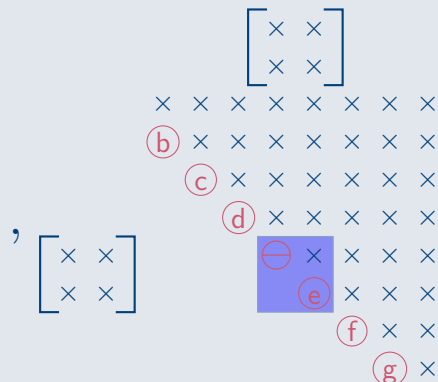
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# Rational QZ: an example

## Swapping poles



*A*



*B*

# Rational QZ: an example

## Swapping poles



*A*

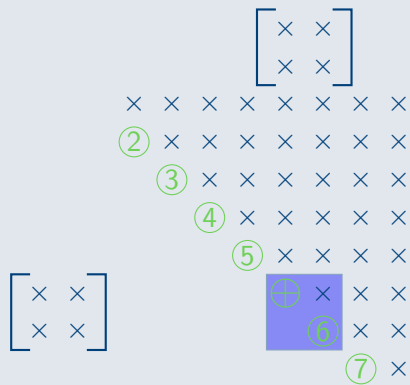
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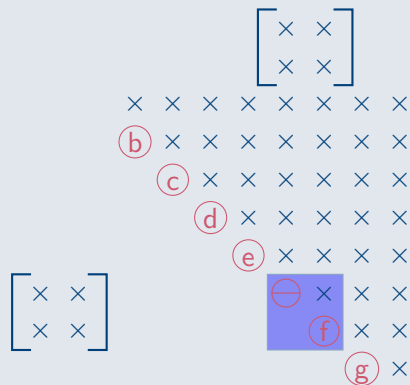
# Rational QZ: an example

## Swapping poles



*A*

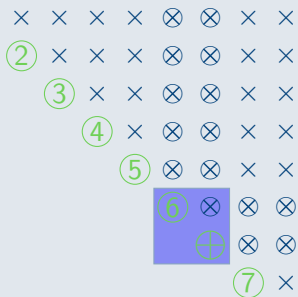
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# Rational QZ: an example

## Swapping poles



*A*

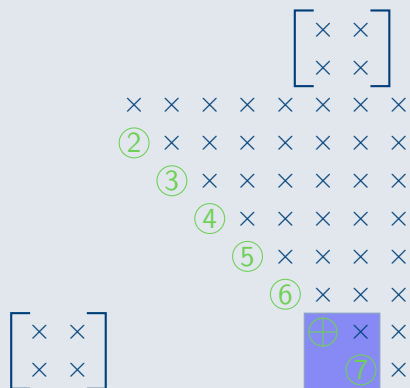
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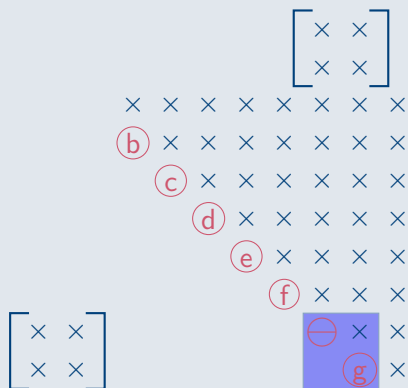
# Rational QZ: an example

## Swapping poles



*A*

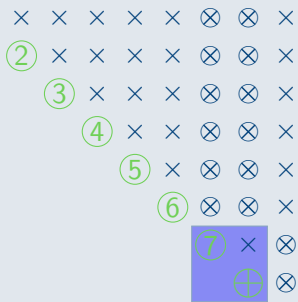
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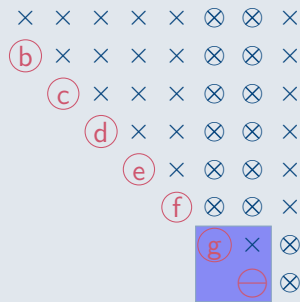
# Rational QZ: an example

## Swapping poles



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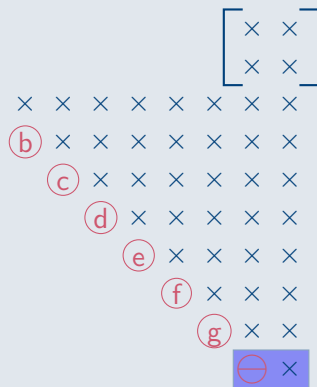
# Rational QZ: an example

## Introducing a pole



*A*

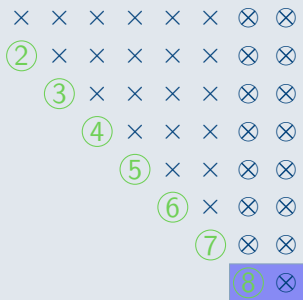
$$\oplus \times \neq \gamma \ominus \times !$$



*B*

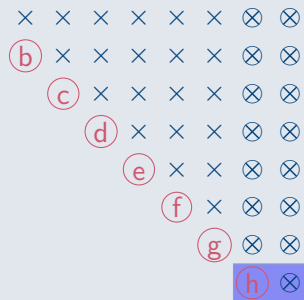
# Rational QZ: an example

## Introducing a pole



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# Classical QZ as a special case

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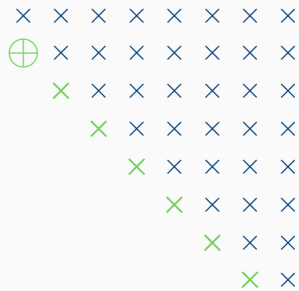
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# Classical QZ as a special case



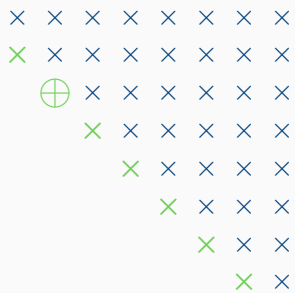
$A$

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$B$

# Classical QZ as a special case



*A*

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*B*

# Theoretical results

Definition: Properness.

The Hessenberg pair  $(A, B)$  is called *proper* if:

1.  $\begin{array}{|c|} \times \\ \hline 1 \end{array} \neq \gamma \begin{array}{|c|} \times \\ \hline a \end{array}$

2.  $\frac{\times}{\times} \neq \frac{0}{0}$

3.  $\begin{array}{|c|} \oplus \times \\ \hline \end{array} \neq \gamma \begin{array}{|c|} \ominus \times \\ \hline \end{array}$

Theorem. (C.-Meerbergen-Vandebril, 2019a)

If  $(A, B)$  is a proper Hessenberg pair with poles  $(\xi_1, \dots, \xi_{n-1})$  distinct from the eigenvalues. Then for  $i = 1, \dots, n$ :

$$\mathcal{K}_i^{\text{rat}}(AB^{-1}, \mathbf{e}_1, (\xi_1, \dots, \xi_{i-1})) = \mathcal{E}_i := \mathcal{R}(\mathbf{e}_1, \dots, \mathbf{e}_i),$$

while for  $i = 1, \dots, n - 1$ :

$$\mathcal{K}_i^{\text{rat}}(B^{-1}A, \mathbf{e}_1, (\xi_2, \dots, \xi_i)) = \mathcal{E}_i.$$

Implicit Q Theorem. (C.-Meerbergen-Vandebril, 2019a)

Given a regular matrix pair  $(A, B)$ . The matrices  $Q$  and  $Z$  that transform it to proper Hessenberg form,

$$(\hat{A}, \hat{B}) = Q^* (A, B) Z,$$

are determined *essentially unique* if  $Q\mathbf{e}_1$  and the (order of the) poles are fixed.



# Theoretical results

Rational accelerated subspace iteration. (C.-Meerbergen-Vandebril, 2019a)

A rational QZ step with shift  $\varrho \notin \{\Lambda, \Xi\}$  on a proper Hessenberg pencil with poles  $(\xi_1, \dots, \xi_{n-1})$  and new pole  $\xi_n$ , all distinct from  $\Lambda$ , performs nested subspace iteration for  $i = 1, \dots, n-1$  accelerated by

$$Q\mathcal{E}_i = \mathcal{R}(\mathbf{q}_1, \dots, \mathbf{q}_i) = (A - \varrho B)(A - \xi_i B)^{-1}\mathcal{E}_i$$

$$Z\mathcal{E}_i = \mathcal{R}(\mathbf{z}_1, \dots, \mathbf{z}_i) = (A - \xi_{i+1} B)^{-1}(A - \varrho B)\mathcal{E}_i,$$

followed by a change of basis.

→ Subspace iteration with rational filter

→ More modular (single swap) convergence theory: (C.-Mach-Vandebril-Watkins, 2019).

## Exactness result (C., 2019)

Let  $(A, B)$  be a proper Hessenberg pencil with poles  $\Xi$ . Furthermore, let  $\varrho$  be an eigenvalue of  $(A, B)$  which is distinct from  $\Xi$ . A rational QZ step,  $Q^*(A, B)Z$ , with shift  $\varrho$  leads to a deflation in the last rows of  $Q^*(A, B)Z$ .

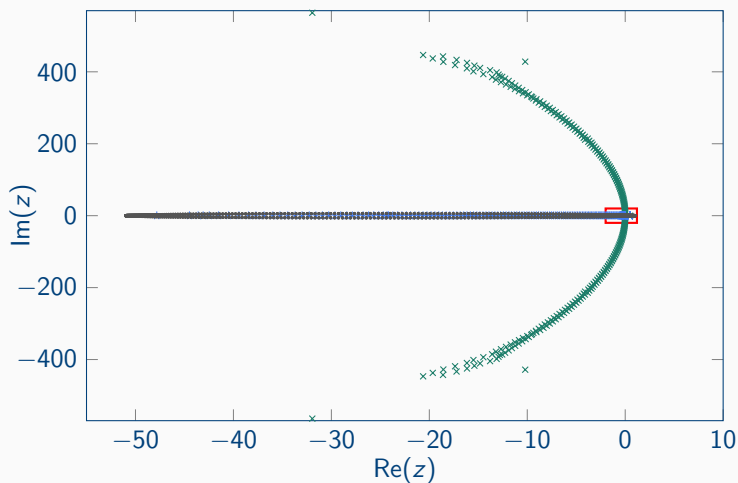
Pole swapping =

- Motivated by **implicit Q theorems**  
⇒ iterates are uniquely determined by  $\mathbf{q}_1 = q(AB^{-1})\mathbf{e}_1$  and poles in pencil
- Nested subspace iteration with a change of basis accelerated by **rational functions** (shifts and poles)

→ These results are based on a connection with **rational Krylov subspaces**

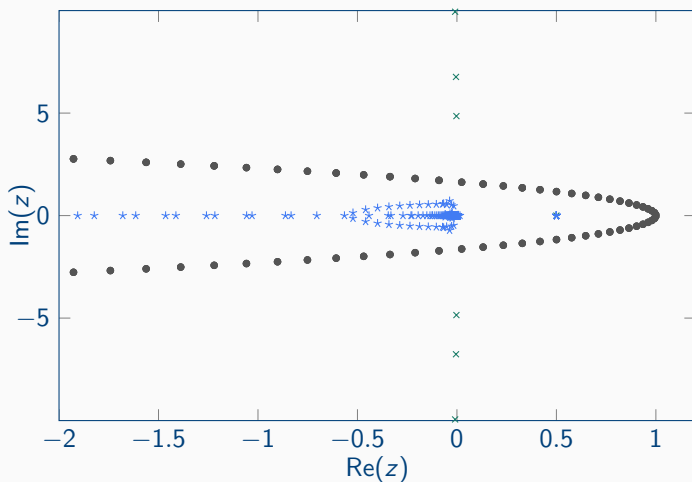
# Numerical example: Reduction to Hessenberg form

Data: MHD matrix pair from MatrixMarket,  $n = 1280$



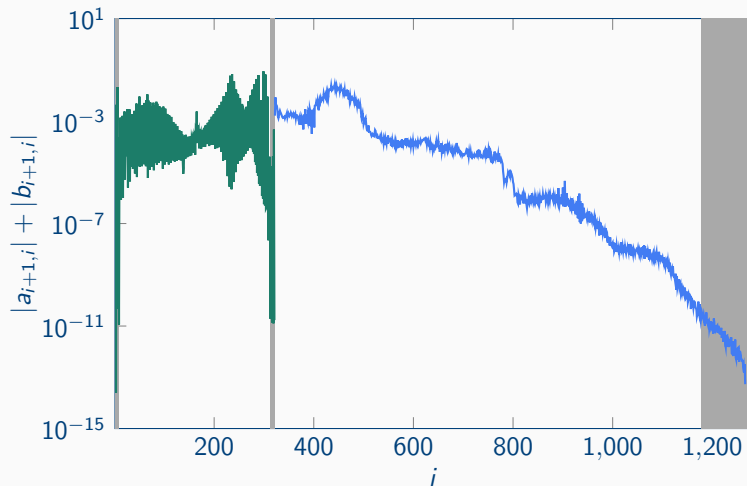
# Numerical example: Reduction to Hessenberg form

*Data:* MHD matrix pair from MatrixMarket,  $n = 1280$



# Numerical example: Reduction to Hessenberg form

Data: MHD matrix pair from MatrixMarket,  $n = 1280$



Multishift, multipole rational QZ

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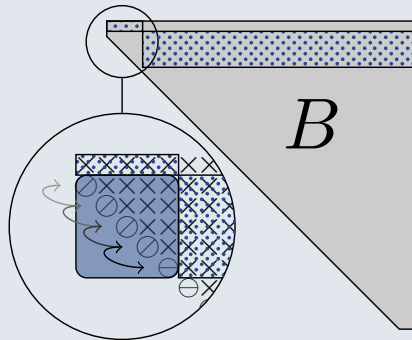
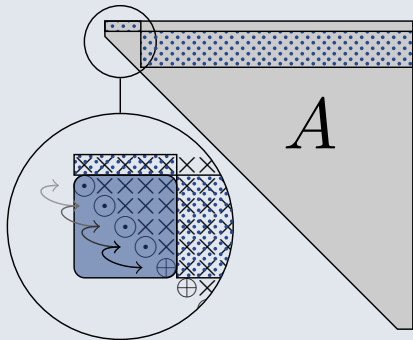
**Motivation:** make the rational QZ method competitive with state-of-the-art.

- Extension of the rational QZ method from Hessenberg to block Hessenberg pencils
- Shifts and poles of larger multiplicity
- Real-valued generalized eigenproblems in real arithmetic
- Swapping  $2 \times 2$  blocks: Iterative refinement via Newton steps (C.-Mastronardi-Vandebril-Van Dooren, 2019).



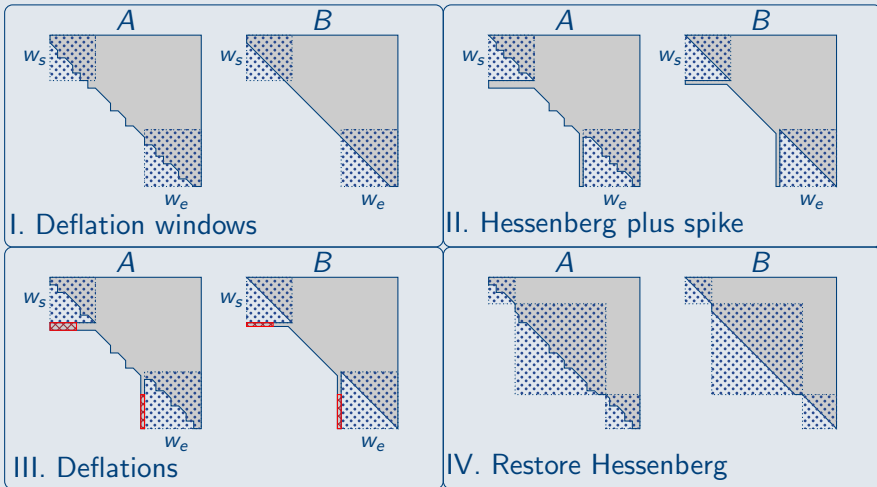
# Multishift, multipole rational QZ

## Batched operations



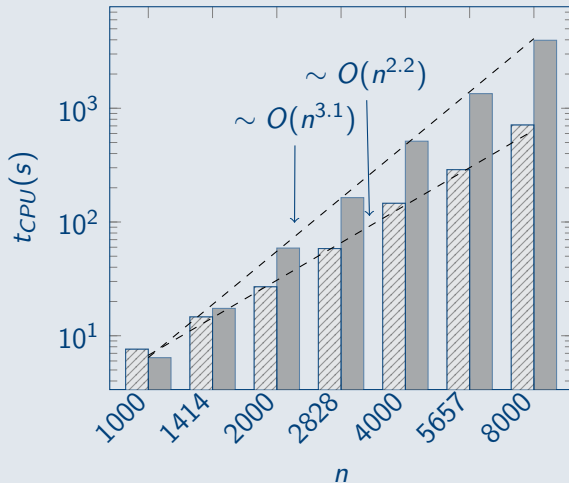
# Multishift, multipole rational QZ

Aggressive early deflation (Braman-Byers-Mathias, 2002)



# Multishift, multipole rational QZ

Numerical experiments with libRQZ v0.1



## Conclusion

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1. We have presented a novel interpretation of QR-type methods:

*bulge chasing*  $\leftrightarrow$  *pole swapping*.

2. This results in a more general class of algorithms.
3. Convergence is determined by rational functions instead of polynomials.
4. Faster and more flexible eigensolvers.

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